

Roadstar Configuration Instruction Manual





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This instruction manual describes how to set parameters for software built inside GPS/GPRS vehicle tracking device **Roadstar**.

Software is used to collect and send data to <u>www.tracking.rs</u> server or some other user server. We will describe how to set parameters for GPRS, GPS and server.

Roadstar parameter configuration can be achieved in two ways. Via **SMS** messages or using **Roadstar** terminal application.

Configuration via SMS

Configuration of **Roadstar** via SMS messages is achieved by sending SMS messages to device in a specific format.

NOTE: Take care of blank space after reserved words! Marked as "_" in following text! In SMS type blank space!

Configuration messages:

Each configuration message begins with *Road#:* followed with next configuration words and parameters if they exist for configuration word (no blank space after *Road#:*).

- Setting vehichle ID

Configuration word and parameter: *ID_vehichleID* where *ID* is configuration word, and *vehichleID* is id for specific vehichle (for instance 23).

Example: Road#:ID_23

- Setting GPRS, server and additional parameters

Configuration word and parameters: *NTS_,p1,p2,p3,p4,p5,p6,p7,p8,p9,p10,p11,p12,p13,* where *NTS* is configuration word and *p(i)* i from 1 to 13, is parameter:

- p1 gprs apn (access point name)
- p2 gprs user (user for GPRS profile defined by mobile operator)
- p3 gprs password (password for GPRS profile defined by mobile operator)
- p4 server IP address (if you use <u>www.tracking.rs</u> leave empty)
- p5 server port (if you use <u>www.tracking.rs</u> leave empty)
- p6 gps scan move interval (in seconds) Cyclic sending data in movement
- p7 gps scan still interval (in seconds) Cyclic sending data while still
- p8 running mode (on speed 0, or on contact 1) is move to stop and stop to move,

detected by measured speed via GPS or by state of contact 3 on 10-wire cable

p9 – scan angle (in degrees) – Is event of vehichle movement created by change of movement direction in degrees (if 0, event is not created)



- p10 scan length (in meters) Same as previous, but in case of made distance
- p11 measure distance by pulse counter (1-by contact 4, 0-by GPS) Is distance measured by
- GPS or by measuring impulses on contact 4 of 10-wire cable
- p12 work in roaming (1-yes, 0-no)
- p13 vehichle ID (number, for instance 1)

example: Road#:NTS , internet, telenor, gprs, 111.222.333.444, 21, 1, 20, 10, 0, 45, 25, 1, 1,

If you are a user of <u>www.tracking.rs</u> for server IP address enter 178.238.232.204, and for server port enter 4022.

example 2 if you use <u>www.tracking.rs</u> : Road#:NTS ,internet,telenor,gprs, 178.238.232.204,4022,1,20,10,0,45,25,1,1,

NOTE: When sending new configuration, always send all mentioned parameters!

Device will respond with message, if setup was correct!

- Reset modem

Configuration word and parameter: *RSTN* action performed: resets modem (turn off, turn on modem).

- Set server IP address

Configuration word and parameter: *serIP_ipAddress* where *serIP* is reserved word, and *ipAddress* is new IP address of server.

- Set scan move interval

Configuration word and parameter: *RefTm_interval* where *RefTm* is reserved word, and *interval* is time interval for scan check in seconds.

- Delete database

Configuration word and parameter: *DelDB* deletes all parameters in modem

- Set server port

Configuration word and parameter: *serPO_numPort* where *serPO* is reserved word and *numPort* is new number for server port. sets new value for server port

- OTAP

Configuration word and parameter: *OTPNOW* performs software update via GPRS

- IO PINs status

Configuration word and parameter: *STAT* Modem returns current status with following informations:

IN:in1in2in3 – current values of input contacts (input1, input2, input3), for example 010; one digit for one contact (0-low, 1-high)
OUT:out1out2out3 – current values of output contacts (output1, output2, output3), for example 100; one digit for one contact (0-low, 1-high)
GPS:numberOfSatelites – current number of available satelites
LAT:value lat – current latitude
LON:value lon – current longitude
SPE:value km/h – current speed

- Set OUTPUT PINs value

With this message, you can set values for output contacts (1-high, 0-low) for output pins out1, out2 and LED output pin.

Configuration word and parameters: OUT: out1out2outLED

Simply enter 1 or 0 for each output contact – for example 101 will switch out1 to 1, out2 to 0 and LED contact to 1.

Configuration via Roadstar Terminal application

Configuration of **Roadstar** can be also achieved using *Roadstar Terminal* application. Connect **Roadstar** via serial cable to your PC. Modem is connected to PC via serial cable as shown in the following picture. After connecting to PC, connect device to power supply.







NOTE: Do not connect device to PC using USB cable! PC port shown on previous picture is RS232! Connect device to PC only using cable shown on previous picture!

Select COM (serial) port on which your device is connected, choose speed 115200bps and press TEST to check connection.

M8	•
5200	

After connection has been established, you can check signal strength, read SIM card number, modem IMEI number, reset or restart modem, execute AT commands.

ignal strengnt	43%
🎺 read SIM number	8938101070710774195
🛷 read IMEI	353815010296725
🋷 Reset	Restart
I send AT command	at+csq +CSQ: 15,0 OK
🧼 Read version	73

User and APN (Access Point Name) settings

APN settings (Access Point Name) are implied settings for each device which is using SIM cards for transferring data via GPRS protocol.

Each Mobile Operator gives for that kind of settings its Access Point Name, Username and Password. **Roadstar** is programmed to recognize these settings for at least 90 different Operators and Telecommunication Companies, over the world.

If **Roadstar** does not recognize Operator parameters for inserted SIM card (Operator isn't on the known list), settings must be entered manually.

Settings can be read from the terminal by pressing READ button, and sent to the terminal with SEND button.

Description must be entered for each user. After naming and giving id for users, ADD button adds user to the list. Users on the list can be saved and loaded each time you want to make a change. Users can be removed from the list as well.

Note: When loading user, APN (access point) data is also loaded. These data is shown on the following page.

	apn	user	pass	
	internet	mobtel	gprs	
		-		
			ad 🚽 🛹 send	
User i	.d			
		lagaristian	l	-
	user c	lescription	Iucb	
		user id	123	
				7
	a 6	101	remove	
	descript	ion	ht	
ср	descript.	ion	id 123	
ıcp	descript	ion	id 123	
юр	descript	ion	id 123	
ıcp	descript	ion	id 123	
ıcp	descript	ion	id LZ3	
ıcp	descript	ion	id 123	



GPS General Settings

In these text boxes, scan and send values are shown. After entering of values which are representing:

- *NOT MOVE TIME* period (in seconds), between sending position data of the vehicle if it doesn't move;
- *RUNNING TIME* period (in seconds), between sending position data of the vehicle if it is on the move;
- ANGLE (in degrees), when data of turning of the vehicle is send;
- LENGTH (in meters), represents period after how many meters data is being send,
- SERVER ADDRESS server IP address
- SERVER PORT server port

Check boxes allow other additional settings.

Press READ button to get current parameters, or SEND for setting new ones.

Note: Check course box will be checked after reading data, depending on value entered into field for *angle*. If angle is less then 25 degrees, box will be unchecked, i.e. no course checking.

scan and send values-						
not move time(s)	300 🗸	work in roaming				
running time(s)	15	check distance				
angle (deg)	30	check course				
length (m)	400 🗸	run mode on pin				
		run mode on speed				
	×	measure by PLSC				
		expand still interval				
server						
server address	[111.222.333.444				
server port	1234					
	·					
🛷 read		🧼 send				

User's vehichle

Type selection of the vehicle is in the drop down list, after that it is required to enter vehichle's id number.

Adding to the list can be performed by pressing the ADD button,

and removing the unwanted type from the list with the REMOVE button.

(Select vehichle first)

Press READ button to read current parameters from device, or SEND to set new ones.



After setting all parameters, device is ready to be installed in vehicle, and you can start tracking it. For **Roadstar** installation check document **Roadstar Installation Instruction Manual.**